

Hierarchical nowcasting of counts with an application to COVID-19 hospitalisations in Germany

SACEMA seminar

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May 13, 2022

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Introducing the nowcasting problem

Introduction - General problem statement

- Infectious disease data is created by an underlying infection process.
- Infections are generally unobserved.
- We observe other related measures such as the onset of symptoms, test positivity, hospital admission, and death.
- All of these measures happen with some delay from the original date of infection and depending on the disease we may know more or less about these delays.
- When we observed any of these measures we truncate this delay and so only observe some of data that will eventually be reported.

Introduction - Aims of nowcasting

Core aim

Estimate what will ultimately be reported for proxies of infection that we observe with truncation due to their delay from the date of infection.

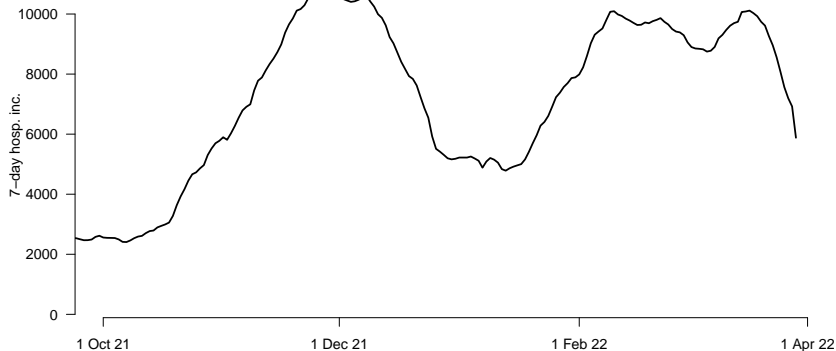
Secondary aims

- Provide improved situational awareness in real-time contexts.
- Estimate the underlying distributions for use in other contexts and to improve understanding of the disease system.
- Improve forecasts of the truncated observations.

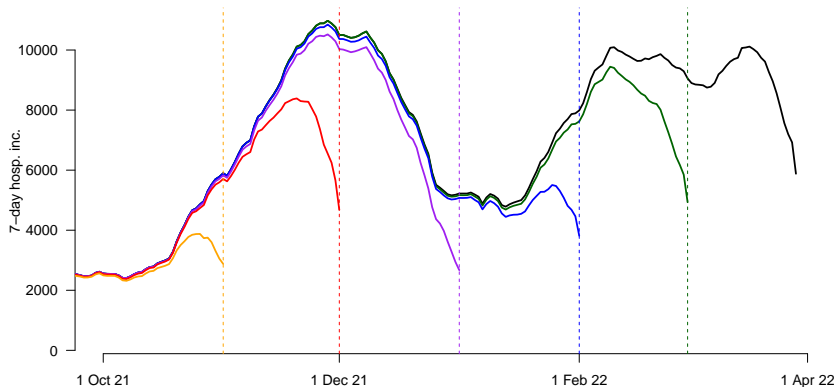
A German example - Seven day hospitalisation incidence

- **Definition:** The number of persons, who over a seven-day period
 - have been registered electronically as a COVID-19 case by a local health authority (*Meldedatum*).
 - and have been hospitalized (not necessarily during the seven-day period).
- This is **not** the number of new hospitalizations over the last seven days.
- This number does **not** take into account whether COVID-19 was the reason of hospitalization.
- **Most recent values are biased downwards due to two types of delays:**
 - delay between *Meldedatum* (\approx positive test) and hospitalization.
 - delay between hospitalization and appearance in RKI data.

A German example - What does the data look like?



A German example - What does the data look like?

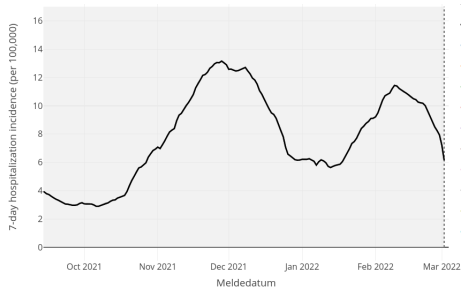


A German example - What are we trying to do and why?

Goal

Estimate (predict) what preliminary/incomplete values will ultimately look like.

- In a way this is a *forecast* rather than a *nowcast*: some hospitalizations in question have not yet happened.
- Important to estimate as well as possible as this indicator is used as a key indicator by policy-makers in Germany.

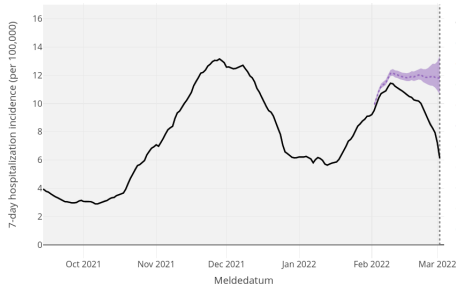


A German example - What are we trying to do and why?

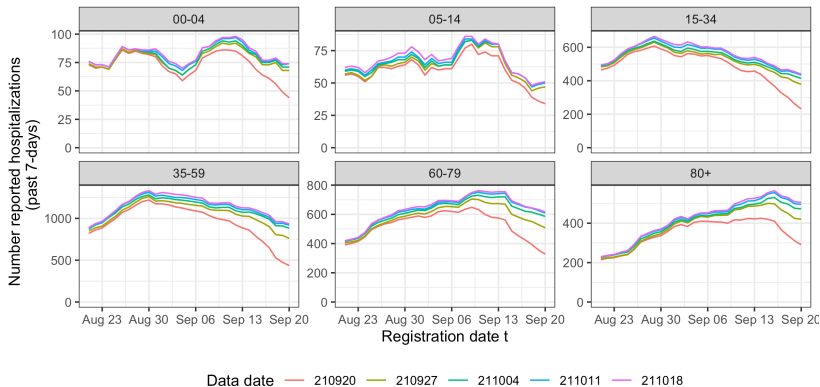
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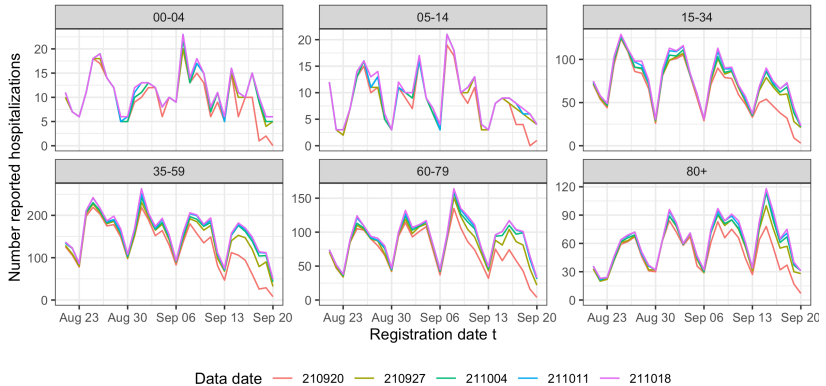
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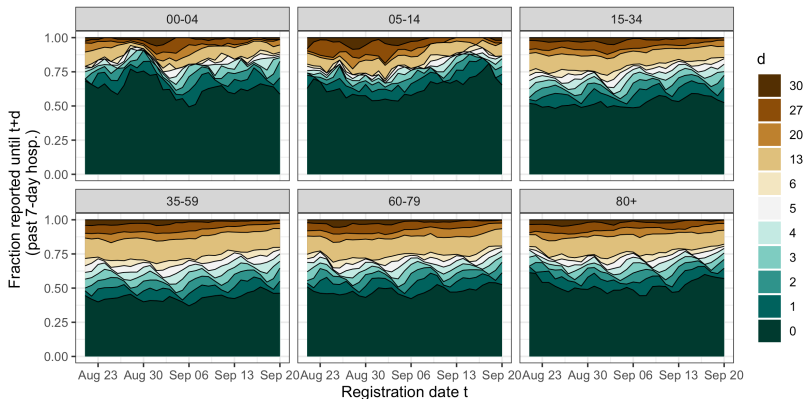
A German example - Age and region stratified



A German example - underlying data has a strong day of week signal



A German example - What about reporting delays?



A German example - Summary

- Seven day hospitalisation incidence by date of positive test is used as a key indicator in Germany.
- These data are truncated and ignoring this may lead to biased surveillance measures and flawed disease making.
- The data is age and location stratified.
- Both incidence and reporting has a strong weekly structure.
- Reporting delays appear to vary over time and by strata.

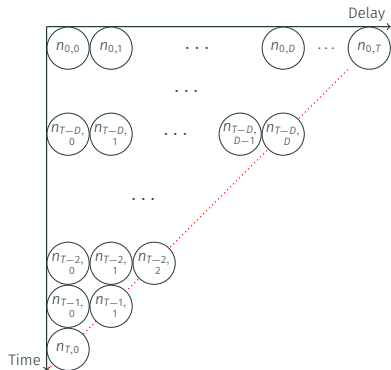
The nowcasting aim in this context

Estimate hospitalisations for registration days from the number of already reported hospitalisations and the date of these reports.

The statistical problem - Completing the reporting triangle

Available data at Day T ('now'), per strata $s = 1 \dots, S$:

- $n_{t,d,s}$: Number of individuals with registration (reference) at day t , reported hospitalization (report) d days after (i.e. at Day $t + d$) for all $t + d \leq T$
- $N_s(t, T) = \sum_{d=0}^{T-t} n_{t,d,s}$: Overall number of individuals registered at Day t and reported hospitalization up until day T (now)

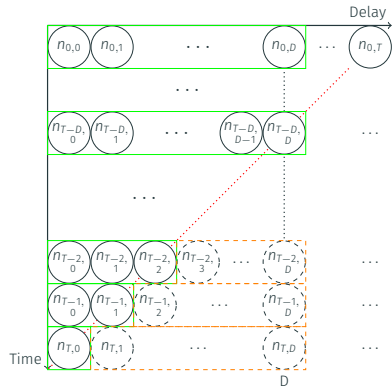


The statistical problem - Completing the reporting triangle

Aim of nowcasting:

- Predict $N_s(t, \infty) = \sum_{d=0}^{\infty} n_{t,d,s}$ for all days $t \leq T$ based on available information at day T
- Corresponds to the prediction of (so far unseen) $N_s(t, \infty) - N_s(t, T)$
- In practice, one defines a maximum reporting delay D , e.g. $D = 35$ days,

$$N_s(t, \infty) = \sum_{d=0}^D n_{t,d,s}$$




The Germany nowcasting hub

The Germany nowcasting hub - Multi-model nowcasting

- Experience from weather and infectious disease forecasting (i.e the CDC and ECDC forecasting hubs) shows that combining different models can improve predictions.
- The hub collects and combines probabilistic nowcasts from 8 independently run models.
- Daily submissions to a public GitHub repository:

main • [hospitalization-nowcast-hub](#) / [data-processed](#) / [KIT-simple_nowcast](#) / 2022-03-29-KIT-simple_nowcast.csv

 dwolffram Update Baseline ✓ Latest commit

1 contributor

5337 lines (5337 sloc) | 472 KB

Q Search this file...

| | location | age_group | forecast_date | target_end_date | target | type | quantile | value | pathogen |
|---|----------|-----------|---------------|-----------------|----------------------|----------|----------|-------|----------|
| 1 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | mean | NA | 10642 | COVID-19 |
| 2 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | quantile | 0.025 | 8521 | COVID-19 |
| 3 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | quantile | 0.1 | 9131 | COVID-19 |
| 4 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | quantile | 0.25 | 9753 | COVID-19 |
| 5 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | quantile | 0.5 | 10534 | COVID-19 |
| 6 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | quantile | 0.75 | 11413 | COVID-19 |
| 7 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | quantile | 0.9 | 12292 | COVID-19 |
| 8 | DE | 00+ | 2022-03-29 | 2022-03-29 | 0 day ahead inc hosp | quantile | 0.9 | 12292 | COVID-19 |

<https://github.com/KITmetricslab/hospitalization-nowcast-hub/tree/main/data-truth/COVID-19>

The Germany nowcasting hub - Interactive online platform

<https://covid19nowcasthub.de/>

covid19nowcasthub.de

Nowcasts

Hintergrund (DE)

Background (EN)

Kontakt



Nowcasts der Hospitalisierungsinzidenz in Deutschland (COVID-19)

Sprache / language

☒ Deutsch ☐ English

Datenstand



2022-03-29



Nowcasts werden täglich gegen 13:00 aktualisiert, können aber verspätet sein falls Daten des RKI verzögert veröffentlicht werden. Falls ein Nowcast für das gewählte Datum nicht vorliegt wird der aktuellste Nowcast der letzten 7 Tage gezeigt.

Stratifizierung

☒ Bundesland ☐ Altersgruppe

Bundesland

Alle (Deutschland)

Beachten Sie beim Vergleich der Altersgruppen bzw. der Bundesländer die unterschiedlichen Skalen in der Grafik.

Grafische Darstellung:

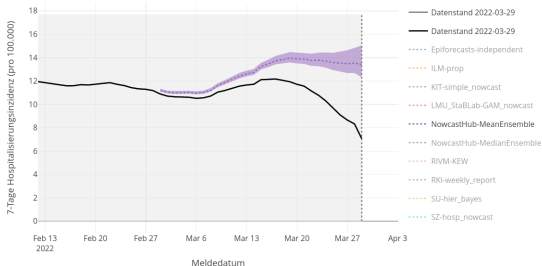
☒ Interaktiv für mehrere Modelle
☐ Überblick für ein Modell

☐ Zeige Übersichtstabelle

☐ Zeitreihe eingefrorener Werte

Diese Plattform vereint Nowcasts der 7-Tages-Hospitalisierungsinzidenz in Deutschland basierend auf verschiedenen Methoden, mit dem Ziel einer verlässlichen Einschätzung aktueller Trends. Detaillierte Erläuterungen gibt es unter "[Hintergrund](#)".

Bei Unregelmäßigkeiten im Meldeprozess durch z.B. starke Belastung des Gesundheitssystems oder Feiertage kann die Verlässlichkeit der Nowcasts beeinträchtigt werden.



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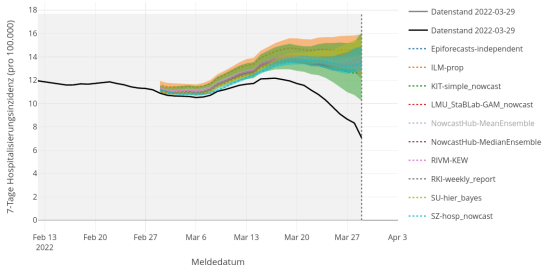
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The Germany nowcasting hub - Approaches taken by different teams

Main sources of information on unknown values

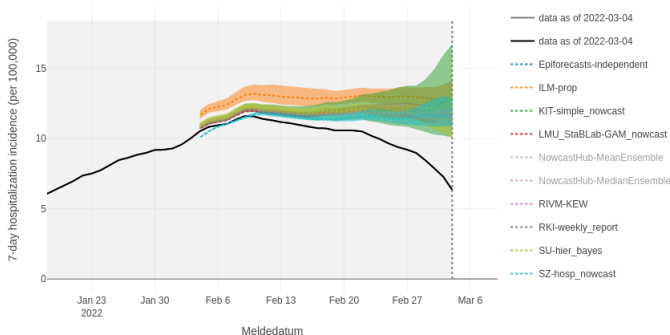
- Incomplete hospitalization numbers for same day
- Incomplete hospitalization numbers from surrounding days
- Case numbers

Strategies to extrapolate the reporting triangle

- Multiplication factors (KIT, RKI, SZ).
- Regression with splines for smooth time trends (RIVM Bilthoven, LMU Munich)
- Random walk / autoregression and parametric delay distributions (**epinowcast** - **LSHTM**, Stockholm University)
- Regression on case incidences (TU Ilmenau)

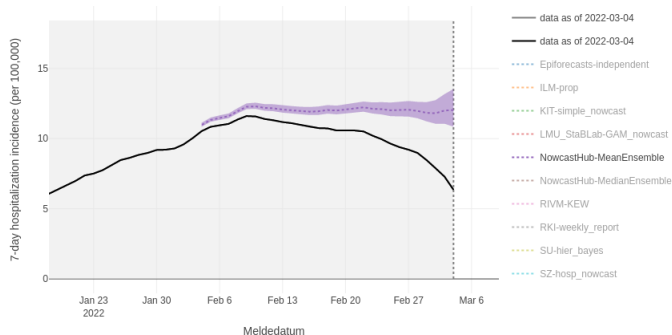
The Germany nowcasting hub - The ensemble

- The main output of the platform is an **ensemble nowcast**, i.e. combination of all available models.
- It is obtained as a simple quantile-wise mean (or median) of the different submissions.
- Johannes's idea: We hope that similarly many models will be off upwards and downwards.

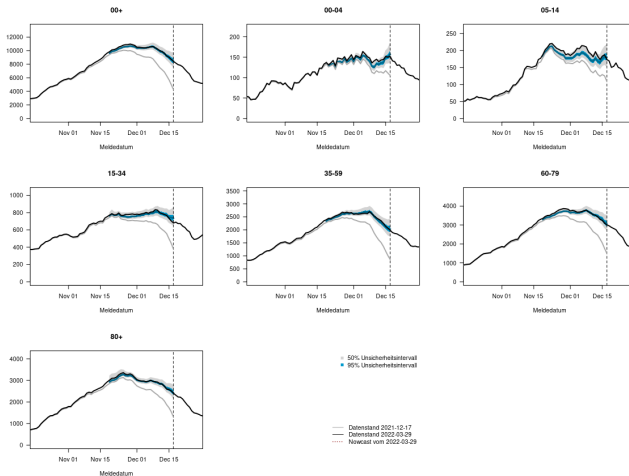


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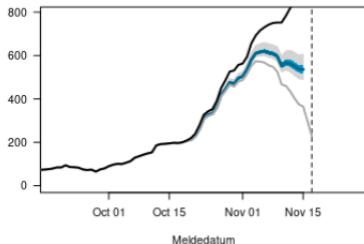


The Germany nowcasting hub - The ensemble is pretty good

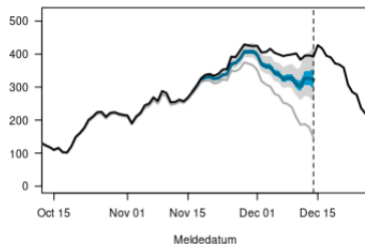


The Germany nowcasting hub - ... except when it isn't.

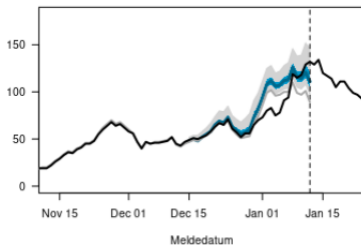
Sachsen



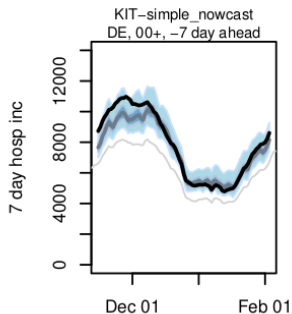
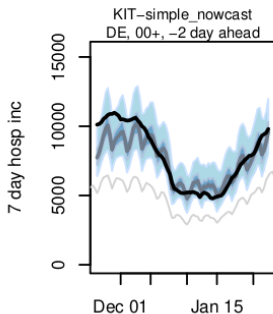
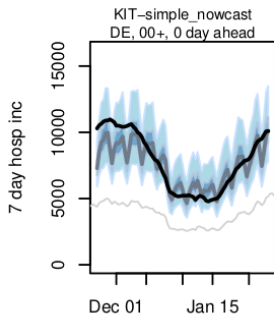
Rheinland-Pfalz



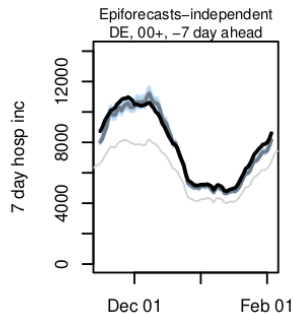
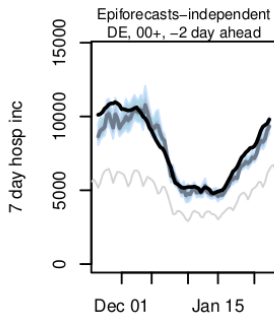
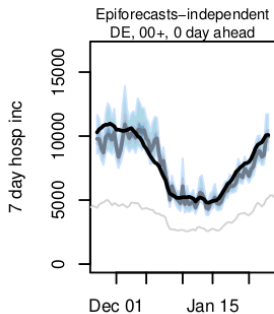
Bremen



The Germany nowcasting hub - How well do individual models work?



The Germany nowcasting hub - How well do individual models work?



The Germany nowcasting hub - Pre-registered evaluation study

- The hub team are conducting a systematic evaluation study of real-time nowcasts from different methods.
- This study has been pre-registered (<https://osf.io/mru75/>) and runs from Nov 2021 through Apr 2022.

The screenshot shows the OSF Registries interface. At the top, there's a dark navigation bar with the OSF logo and 'OSF REGISTRIES' on the left, and links for 'Add New', 'My Registrations', 'Help', 'Donate', 'Join', and 'Login' on the right. Below this is a light blue banner with a message about spam content. The main title of the registration is 'Comparison and combination of real-time COVID19 forecasts in Germany and Poland', with a sub-label 'Public registration'. A left sidebar contains a menu with 'Overview' (selected), 'Files', 'Wiki', 'Components' (0), 'Links' (0), 'Analytics', and 'Comments' (0). The main content area has a 'Summary' section with a hamburger menu icon, containing a paragraph about the registration's purpose and a link to 'Preregistration.pdf'. To the right of the summary is a 'Contributors' section listing 'Johannes Bracher' and a 'Description' section with a paragraph about the study's goals.

OSF REGISTRIES ▾ Add New My Registrations Help Donate Join Login

have increased our measures to flag spam content on OSF. Contact support@osf.io if you believe your content has been flagged in error.

Comparison and combination of real-time COVID19 forecasts in Germany and Poland

Public registration ▾

- Overview
- Files
- Wiki
- Components 0
- Links 0
- Analytics
- Comments 0

Summary

Provide a narrative summary of what is contained in this registration or how it differs from prior registrations. If this project contains documents for a preregistration, please note that here.

This registration serves to ensure a transparent set of rules and criteria to guide the study. Details are provided in the attached PDF.

Add supplemental files or additional information

- Preregistration.pdf

Contributors

Johannes Bracher

Description

Short-term forecasts of cases, deaths and hospitalizations can improve situational awareness and provide an additional element to inform public health decision making during the COVID19 pandemic. While early in the pandemic only few prediction models were available, there is now a growing number of forecasts based on diverse methods and data streams. This project

A quick tangent into forecast evaluation

Proper scoring rules

The highest expected reward is given if the true probability distribution is supplied as the forecast.

Here the continuous ranked probability score (CRPS) and its approximate cousin the weighted interval score (WIS) are used to evaluate forecasts.

The CRPS is defined as,

$$\text{CRPS}(F, y) = \int_{-\infty}^{\infty} (F(x) - \mathcal{H}(x \geq y))^2 dx$$

F is the CDF, \mathcal{H} is a step function, y is the true value, and x is the forecast.

A quick tangent into forecast evaluation

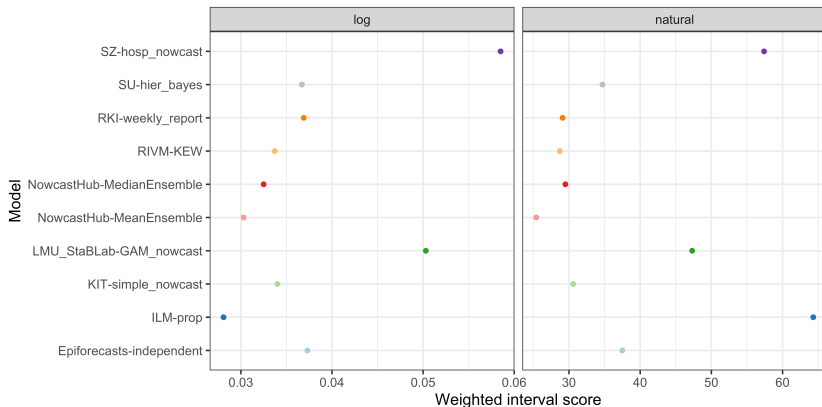
Proper scoring rules

The highest expected reward is given if the true probability distribution is supplied as the forecast.

- Very impressive.
- Essentially this is a generalisation of absolute error to a probabilistic setting.
- If we take the log of observations and forecasts and calculate the CRPS it becomes an approximate generalisation of the relative error
- Nikos Bosse (PhD student @LSHTM and author of the `scoringutils` R package) is doing more work on this as we speak (or he better be).

The Germany nowcasting hub - Preliminary Evaluation

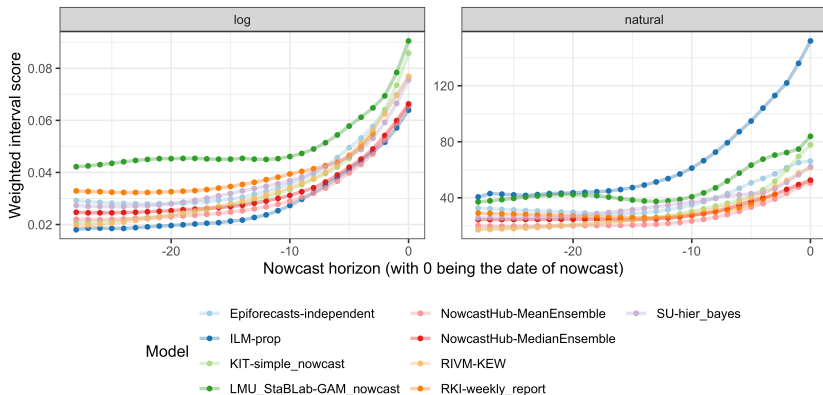
Overall:



See more: <https://epiforecasts.io/eval-germany-sp-nowcasting/>

The Germany nowcasting hub - Preliminary Evaluation

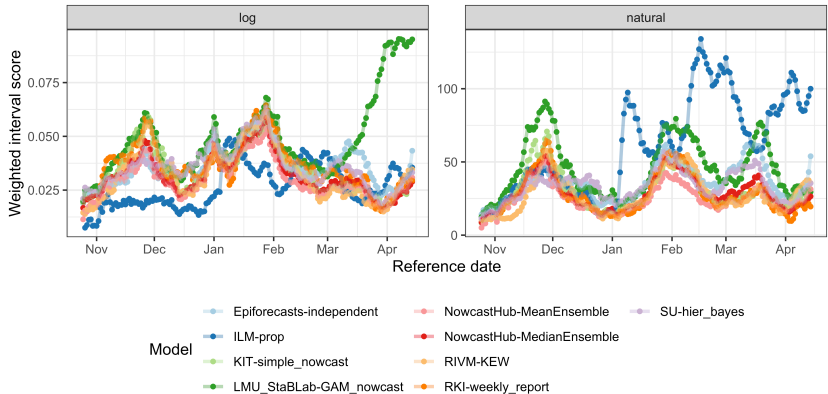
By horizon:



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The Germany nowcasting hub - Preliminary Evaluation

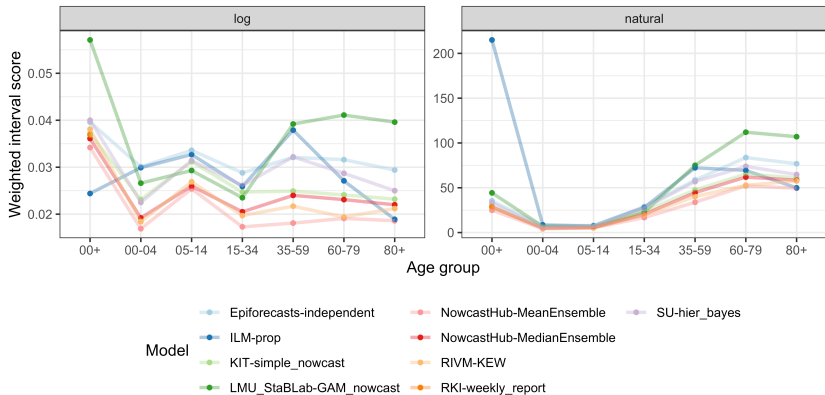
By date of test positivity:



See more : <https://epiforecasts.io/eval-germany-sp-nowcasting/>

The Germany nowcasting hub - Preliminary Evaluation

By age group:



See more : <https://epiforecasts.io/eval-germany-sp-nowcasting/>

The Germany nowcasting hub - Summary

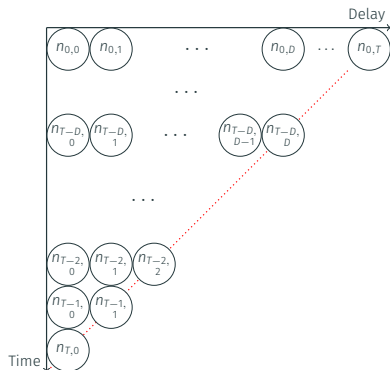
- In most cases, nowcasts have conveyed a good picture of actual trends.
- Most methods are a bit confident
- Sometimes even the ensemble of all models is very clearly wrong.
- The hub ensemble is generally somewhat better than any individual model
- Collaboratively comparing models allows us to learn about which methods work best.
- The nowcasts have been used by numerous media outlets (Die Zeit, Süddeutsche Zeitung, Der Spiegel, Focus, Science Media Center Germany).

The epinowcast model

The statistical problem - Completing the reporting triangle

Available data at Day T ('now'), per strata $s = 1 \dots, S$:

- $n_{t,d,s}$: Number of individuals with registration (reference) at day t , reported hospitalization (report) d days after (i.e. at Day $t + d$) for all $t + d \leq T$
- $N_s(t, T) = \sum_{d=0}^{T-t} n_{t,d,s}$: Overall number of individuals registered at Day t and reported hospitalization up until day T (now)

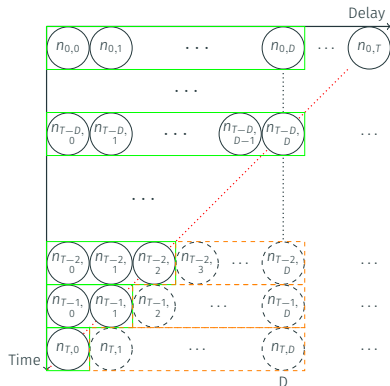


The statistical problem - Completing the reporting triangle

Aim of nowcasting:

- Predict $N_s(t, \infty) = \sum_{d=0}^{\infty} n_{t,d,s}$ for all days $t \leq T$ based on available information at day T
- Corresponds to the prediction of (so far unseen) $N_s(t, \infty) - N_s(t, T)$
- In practice, one defines a maximum reporting delay D , e.g. $D = 35$ days,

$$N_s(t, \infty) = \sum_{d=0}^D n_{t,d,s}$$



The epinowcast model - the basic idea

- Building up on Höhle [1], McGough [2], and Günther [3] .
- General idea: separate nowcasting problem into two “sub-models”
 1. Model for the expected number of final notifications
 2. Model for *delay distribution* of the reporting process. This model is further split into 3 sub-models.
 - 2.1 The baseline hazard model.
 - 2.2 The report day hazard model.
 - 2.3 The reference day hazard model.
- Helps to express assumptions in an “interpretable” way.
- When groups of observations (i.e age or location) are present we can either choose to model jointly or independently.

The epinowcast model - expected final notifications sub-model

Here we follow Günther [3] and specify a group specific daily random walk on the log scale. This is generalisable to any model in principle.

$$\log(\lambda_{gt}) \sim \text{Normal}(\log(\lambda_{gt-1}), \sigma_g^\lambda)$$

$$\log(\lambda_{g0}) \sim \text{Normal}(\log(N_{g0}), 1)$$

$$\sigma_g^\lambda \sim \text{Half-Normal}(0, 1)$$

Notation

λ_{gt} : expected number of hospitalizations in group g with a reference date at day $t = 0, \dots, T$

The epinowcast model - delay distribution model

We define the delay distribution (p_{gtd}) as a discrete time hazard model:

$$h_{gtd} = P(\text{delay} = d | \text{delay} \geq d, W_{gtd})$$

We extend this model to decompose W_{gtd} into 3 components:

1. Hazard derived from a parametric delay distribution (γ_{gtd}) dependent on covariates at the date of occurrence.
2. Hazard not derived from a parametric distribution (δ_{gtd}) dependent on covariates at the date of occurrence.
3. Hazard dependent on covariates referenced to the date of report (ϵ_{gtd}).

The epinowcast model - baseline hazard model

We assume that the probability of reporting p'_{gtd} on a given date follows a parametric distribution with the summary parameters defined using reference date indexed fixed (α_i) and random (β_j) coefficients,

$$\begin{aligned}p'_{gtd} &\sim \text{LogNormal}(\mu_{gt}, v_{gt}) \\ \mu_{gt} &= \mu_0 + \alpha_\mu X_\gamma + \beta_\mu Z_\gamma \\ v_{gt} &= \exp(v_0 + \alpha_v X_\gamma + \beta_v Z_\gamma)\end{aligned}$$

The parametric logit hazard for this component of the model is then,

$$\gamma_{gtd} = \text{logit} \left(\frac{p'_{gtd}}{\left(1 - \sum_{d'=0}^{d-1} p'_{gtd'}\right)} \right)$$

If we defined this directly using daily hazard terms we would have defined the Cox model.

The epinowcast model - proportional hazard models

We then define our two sub-models that assume proportional hazards.

These act based on the reference date and report date respectively (i.e the first assumes all reports from a given reference day are impacted and the second assumes all reports that occur on a given day are impacted).

Similar these are specified with fixed (α_i) and random (β_i) coefficients.

$$\delta_{gtd} = \mu_0 + \alpha_\delta X_\delta + \beta_\delta Z_\delta \quad (1)$$

$$\epsilon_{gtd} = \epsilon_0 + \alpha_\epsilon X_\epsilon + \beta_\epsilon Z_\epsilon \quad (2)$$

The epinowcast model - Overall hazard and probability of report

The overall hazard for each group, occurrence time, and delay is then,

$$\text{logit}(h_{gtd}) = \gamma_{gtd} + \delta_{gtd} + v_{gtd}, \quad h_{gtd} = 1$$

The probability of report for a given delay, occurrence date, and group is then as follows,

$$p_{gt0} = h_{gt0}, \quad p_{gtd} = \left(1 - \sum_{d'=0}^{d-1} p_{gtd'}\right) \times h_{gtd}$$

The epinowcast model - Observation model

Expected notifications by time of occurrence (t) and reporting delay can now be found by multiplying expected final notifications for each t with the probability of reporting for each day of delay (p_{gtd}).

$$n_{gtd} \mid \lambda_{gt}, p_{gtd} \sim \text{NB}(\lambda_{gt} \times p_{gtd}, \phi), \quad t = 1, \dots, T.$$

We produce a nowcast of final observed notifications at each occurrence time by summing posterior estimates for each observed notification for that occurrence time.

$$N_{gt} = \sum_{d=0}^D n_{gtd}$$

The epinowcast model - Summary

- Phew that was a lot. Can you see why we need a nice and friendly package!
- This is all really a complex regression.
- We can also think of it as a decomposed regression and survival model (i.e Cox and friends).
- The flexible structure outlined here allows us to define a range of models including day of the week effects, random walks by week etc.

The epinowcast R package

The epinowcast R package - Why?

- Previous nowcasting implementations have either been question specific or rigidly defined.
- The nowcasting hub has highlighted the potential complexity of models.
- It has also highlight issues with comparison as there is no easy way for one researcher to run all the models.
- Nowcasting is at the core of many real-time analysis questions but is often not the focus. We want to improve this step for everyone.

The epinowcast R package - What?

An in development R package:

epinowcast 0.0.0.2000 [Reference](#) [Articles](#) [Changelog](#)

Hierarchical nowcasting of right censored epidemiological counts

CRAN version 0.0.0.2000 [Source](#) [Help](#) [Export to R](#)

DOI: 10.5281/zenodo.5777590

This package contains tools to enable flexible and efficient hierarchical nowcasting of right censored epidemiological counts using a semi-mechanistic Bayesian method with support for both day of reference and day of report effects. Nowcasting in this context is the estimation of the total notifications (for example hospitalisations or deaths) that will be reported for a given date based on those currently reported and the pattern of reporting for previous days. This can be useful when tracking the spread of infectious disease in real-time as otherwise changes in trends can be obscured by partial reporting or their detection may be delayed due to the use of simpler methods like truncation

Installation

Installing the package

Install the stable development version of the package with:

```
install.packages("epinowcast", repos = "https://epiforecasts.r-universe.dev")
```

Install the unstable development from GitHub using the following,

```
remotes::install_github("epiforecasts/epinowcast", dependencies = TRUE)
```

Installing CmdStan

If you don't already have CmdStan installed then, in addition to installing `epinowcast`, it is also necessary to install CmdStan using CmdStanR's `install_cmdstan()` function to enable model fitting in `epinowcast`. A suitable C++ toolchain is also required. Instructions are provided in the [Getting started with CmdStanR](#) vignette. See the [CmdStanR documentation](#) for further details and support.

Links
[Browse source code](#)
[Report a bug](#)

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Community
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Citation
[Citing epinowcast](#)

Developers
[Sam Abbott](#)
Author, maintainer
[Adrian Lison](#)
Author
[More about authors...](#)

Dev status

CRAN

epinowcast

R-CMD-BASH

passing

coverage

100%

See more: <https://epiforecasts.io/epinowcast/>

The epinowcast R package - What?

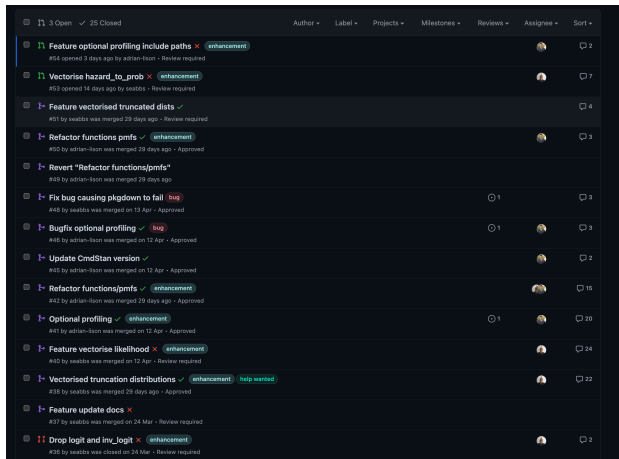
Highly optimised stan implementation:

```
139 model {
140   profile("model_priors") {
141     // priors for unobserved expected reported cases
142     leobs_init ~ normal(eobs_init, 1);
143     eobs_lsd ~ zero_truncated_normal(eobs_lsd_p[1], eobs_lsd_p[2]);
144     for (i in 1:q) {
145       leobs_resids[i] ~ std_normal();
146     }
147     // priors for the intercept of the log normal truncation distribution
148     logmean_int ~ normal(logmean_int_p[1], logmean_int_p[2]);
149     logsd_int ~ normal(logsd_int_p[1], logsd_int_p[2]);
150     // priors and scaling for date of reference effects
151     if (neffs) {
152       logmean_eff ~ std_normal();
153       logsd_eff ~ std_normal();
154       if (neff_sds) {
155         logmean_sd ~ zero_truncated_normal(logmean_sd_p[1], logmean_sd_p[2]);
156         logsd_sd ~ zero_truncated_normal(logsd_sd_p[1], logsd_sd_p[2]);
157       }
158     }
159     // priors and scaling for date of report effects
160     if (nrd_effs) {
161       rd_eff ~ std_normal();
162       if (nrd_eff_sds) {
163         rd_eff_sd ~ zero_truncated_normal(rd_eff_sd_p[1], rd_eff_sd_p[2]);
164       }
165     }
166     // reporting overdispersion (1/sqrt)
167     sqrt_phi ~ normal(sqrt_phi_p[1], sqrt_phi_p[2]) T[0,];
168   }
169   // log density: observed vs model
170   if (likelihood) {
171     profile("model_likelihood") {
172       target += reduce_sum(obs_lupmf, st, 1, flat_obs, sl, csl, imp_obs, sg, st,
173                           rdlurd, srdlh, ref_lh, dpnfs, ref_p, phi);
174     }
175   }
176 }
```

See more: <https://github.com/epiforecasts/epinowcast/blob/main/inst/stan/epinowcast.stan>

The epinowcast R package - What?

Developed in the open on GitHub:



See more: <https://github.com/epiforecasts/epinowcast/pulls>

The epinowcast R package - What?

An active slack and monthly meeting:

epinowcast

features

+ Add a bookmark

Sam Abbott 7:46 PM Friday, April 29th

Borrowing an idea from [@Adrian Lison](https://github.com/epiforecasts/epinowcast/pull/53) <https://github.com/epiforecasts/epinowcast/pull/53>

#53 Vectorise hazard_to_prob

This PR makes use of ideas from [@adrian-lison](#) and implemented [here](#) to vectorise [hazard_to_prob](#). It differs from this implementation in two ways. Firstly it does not assume the complete hazard is available (due to this not being the case in the likelihood call) and therefore does not optimise the probability at the maximum delay. Secondly, it makes use of [log1n](#) for a slight performance boost and numerical stability.

It also adds slight optimisations to [prob_to_hazard](#) so that only required cumulative probabilities are calculated.

Initial testing suggests this gives a small speedup at the cost of slightly less clear code.

Labels **Assignees**

enhancement [@scabbs](#)

epiforecasts/epinowcast Apr 29th Added by GitHub

Adrian Lison 12:18 PM Tuesday, May 10th

Optional profiling also for included .stan files <https://github.com/epiforecasts/epinowcast/pull/54>

#54 Feature optional profiling include paths

This PR extends the optional profiling also to .stan files in the include paths, and moves the whole functionality to a separate function which is called by `erm_model` if required. All manipulated .stan files with profiling statements removed are stored in the same temporary directory.

Implementation details: By using the same folder structure in the temporary directory as in the original include paths, the relative include paths still apply and the model code is not further touched aside from removing the profiling. This should make the approach very robust. Also, the names of the main model and the included file paths are now directly mirrored, so that warnings or errors from stanc stating a... [Show more](#)

Labels **Comments**

enhancement 1

epiforecasts/epinowcast May 10th Added by GitHub

Direct messages

- Slackbot
- Sam Abbott you
- Adrian Lison
- Felix Guenther
- Johannes Bracher
- Ryan Teo
- Sebastian Funk
- + Add teammates

Apps

- GitHub
- OneDrive and SharePoint
- + Add apps

features

Send a message to #features

The epinowcast R package - What?

Case studies:

epinowcast 0.0.6.2000 Reference Articles Changelog

Search for

Hierarchical nowcasting of age stratified COVID-19 hospitalisations in Germany

Sam Abbott

Source: [vignettes/germany-age-stratified-nowcasting.Rmd](#)

In this vignette we explore using `epinowcast` to estimate COVID-19 hospitalisations by date of positive test in Germany stratified by age using several model specifications with different degrees of flexibility. We then evaluate the resulting nowcasts using visual checks, approximate leave-one-out (LOO) cross-validation using Pareto smoothed importance sampling, and out of sample scoring using the weighted interval score and other scoring measures for the single report date considered here. Before working through this vignette reading the model definition is advised (`vignette("model-definition")`)

Packages

We use the `epinowcast` package, `data.table` and `purrr` for data manipulation, `ggplot2` for plotting, `knitr` to produce tables of output, `loo` to approximately evaluate out of sample performance and `scoringutils` to evaluate out of sample forecast performance.

```
library(epinowcast)
library(data.table)
library(purrr)
library(ggplot2)
library(loo)
library(scoringutils)
library(knitr)
```

This vignette includes several models that take upwards of 10 minutes to fit to data on a moderately equipped laptop. To speed up model fitting if more CPUs are available set the number of threads used per chain to half the number of real cores available (here 2 as we are using 2 MCMC chains and have 4 real cores). Note this may cause conflicts with other processes running on your computer and if this is an issue reduce the number of threads used.

On this page

- Packages
- Data
- Data preprocessing
- Models
- Evaluation
- Summary

See more: <https://epiforecasts.io/epinowcast/articles/germany-age-stratified-nowcasting.html>

The epinowcast R package - Summary

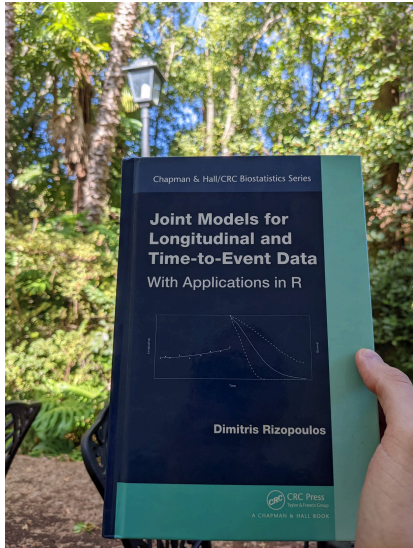
- A flexible nowcasting framework that can fit a range of nowcasting models.
- A community driven package with regular discussions.
- A focus on optimisation and new methodology development.
- Built using software development best practices .
- Evaluated in real-time as part of the Germany nowcasting hub

Extensions

Extensions - Coming soon

- A full featured formula interface.
- A flexible expectation model.
- The ability to forecast into the future.
- An extension to model missing data from Adrian Lison.
- More software development stuff (i.e more tests and documentation).

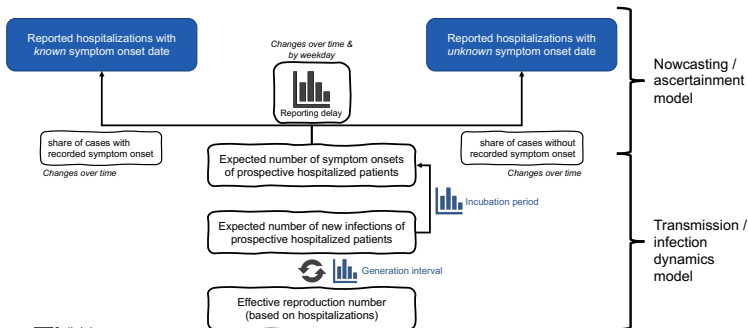
Extensions - Connection to survival models



Extensions - Latent infection modelling using renewal equations

Creating a one stop shop for situational awareness. Spearheaded by Adrian Lison.

Nowcasting R_t from hospitalization linelist data Bayesian hierarchical model



Summary + clapping

Summary

- Because of delays between infections and observation truncation is everywhere when studying infectious disease models.
- Multiple models exist to account for this and most perform quite well.
- In general though these models are not used as part of wider practice.
- The epinowcast R package aims to change that.
- There are lots of exciting use cases and extensions. Please reach out if interested.

References i



Michael Höhle and Matthias an der Heiden.
Bayesian nowcasting during the STEC O104: H4 outbreak in Germany, 2011.

Biometrics, 70(4):993–1002, 2014.



Sarah F McGough, Michael A Johansson, Marc Lipsitch, and Nicolas A Menzies.

Nowcasting by Bayesian Smoothing: A flexible, generalizable model for real-time epidemic tracking.

PLoS computational biology, 16(4):e1007735, 2020.



Felix Günther, Andreas Bender, Katharina Katz, Helmut Küchenhoff, and Michael Höhle.

Nowcasting the COVID-19 pandemic in Bavaria.

Biometrical Journal, 63(3):490–502, 2021.